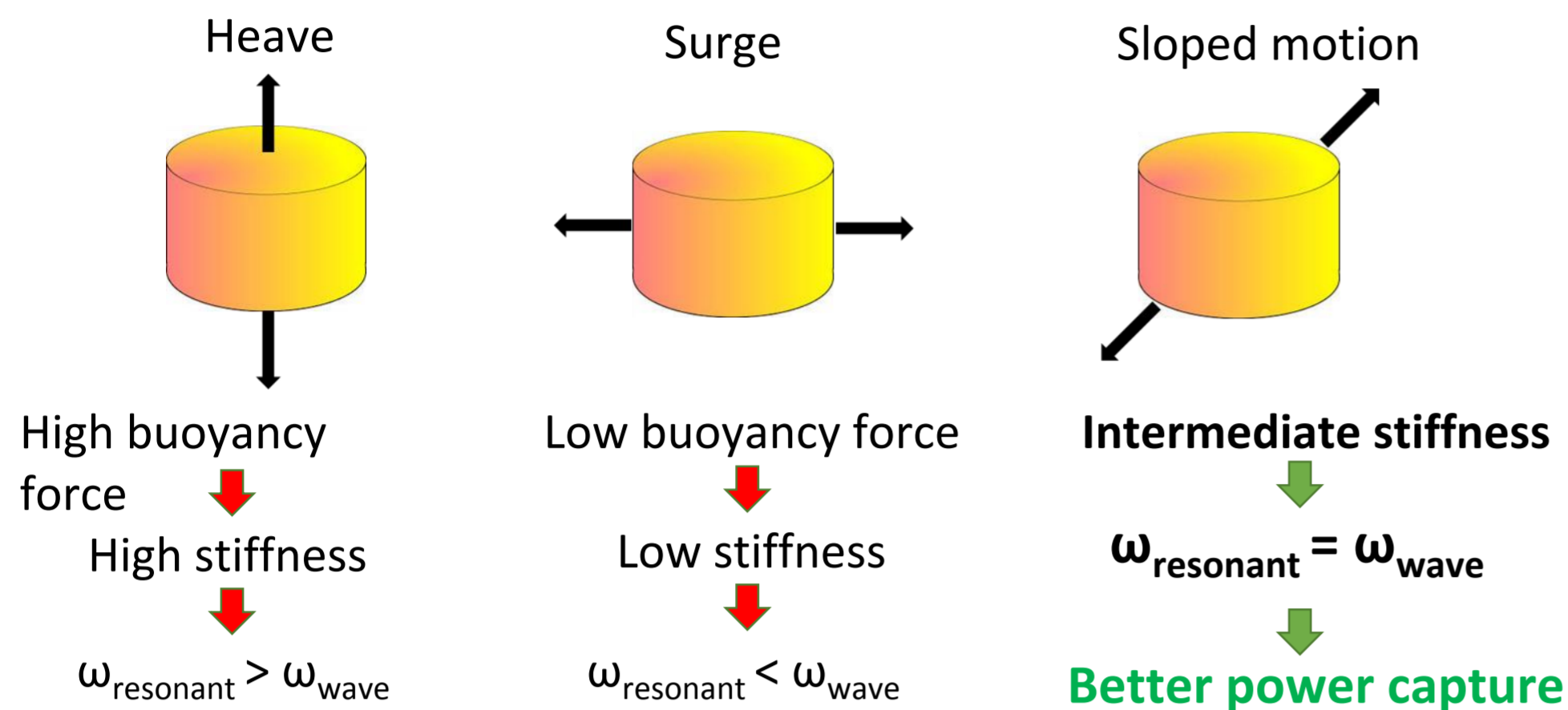
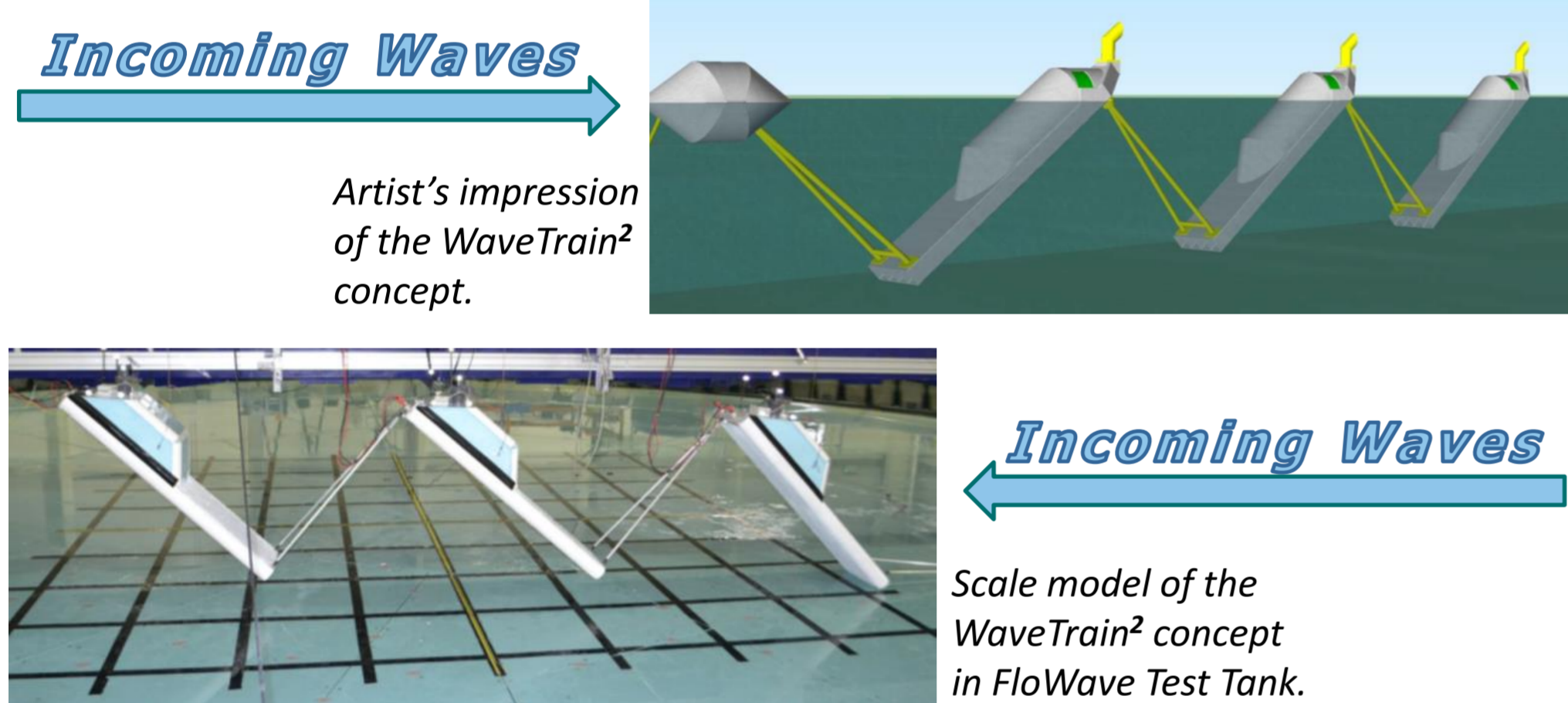


## Motivation



- Previous testing of freely-floating sloped buoys demonstrated that the predicted **large power absorption bandwidth** tended to **collapse** in practice, due to **excessive pitching** about the inclined plane.
- This concept aims to constrain such pitching and retain the wide bandwidth, by connecting multiple sloped modules in series via mechanical struts and rotational joints.
- An **oscillating water column** in each module facilitates power capture.



## Frequency Domain Model

- Generalised modes** of motion enable efficient modelling of the **hinges** and **water columns**, without the need for post-processing.

'N' degrees of freedom

Solve for device motions

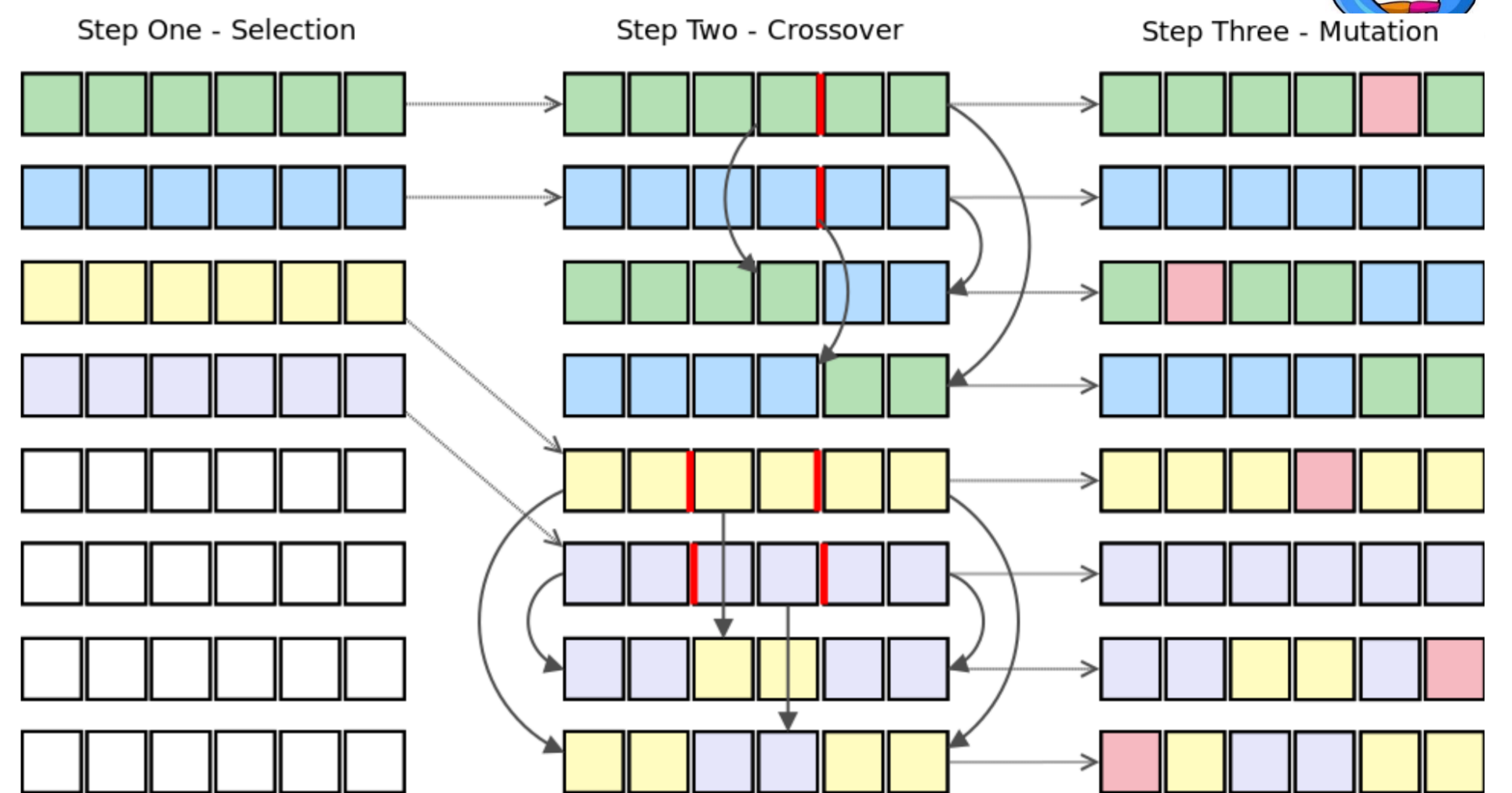
$$\sum_{j=1}^N [-\omega^2 (M_{ij} + A_{ij}) + i\omega B_{ij} + C_{ij}] \xi_j = X_i$$

\*Hydrodynamic (/static) coefficients

WAMIT  
The State of the Art in Wave Interaction Analysis

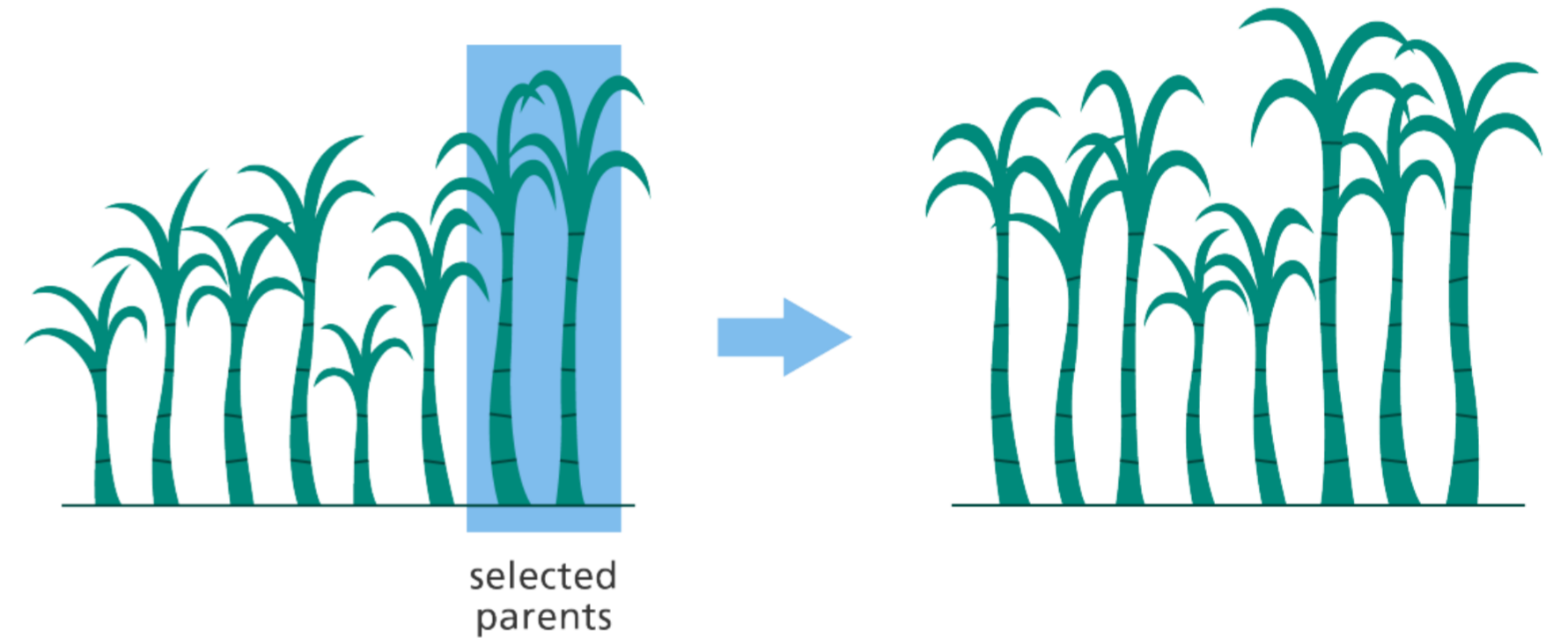
## Genetic Algorithm

### Basic Idea:



Population 1

Population 2



### Implementation:

- Each device must be **statically stable**, rest at the desired **inclination angle**, and have a suitable **waterline** position.  
⇒ Custom algorithm ensures the full set of nonlinear constraints are satisfied.
- Objective function uses hydrodynamic data from WAMIT.

### Model Assumptions:

- Only **in-plane** device motions are significant.
- The **hydrodynamic interactions of the struts** are negligible compared to those of the modules.
- Linear** wave theory applies.
- Power take-off behaviour can be modelled using a linear **damping coefficient** applied to a 'massless lid' on top of each water column.

### Selection Pressures:

- High extracted **POWER** favoured
- Low **MASS** or device **WIDTH** favoured
- Low **JOINT FORCES** favoured

	T <sub>02</sub> (s)									
	5.0	7.0	9.0	11.0	13.0	15.0	17.0	19.0		
0.25	0	0	0	0	0	0	0	0		
0.75	149	219	79	18	0	0	0	0		
1.50	858	2865	1445	508	79	9	0	0		
2.50	0	745	561	324	158	35	0	0		
3.50	0	88	263	61	53	35	9	0		
4.50	0	0	105	35	9	9	9	0		
5.50	0	0	9	26	0	0	0	0		
6.50	0	0	0	0	0	0	0	0		